## OVERVIEW

This general specifications (GS) describes the specifications of the CX1000 control and measurement station.
The CX1000 comes standard with a variety of screens, including control and tuning screens, and is therefore designed for monitoring closed loop control applications. The CX1000 can connect to and acquire control data from up to four external Green series controllers via RS422 MODBUS RTU serial communications. In addition, it allows controller parameters to be manipulated and set as necessary. Using the Ethernet interface equipped as a standard feature, it is possible to send emails, monitor the site remotely on the Web, and make an FTP-based file transfer.

## DISPLAY SPECIFICATIONS

Display unit: $\quad 5.5$-inch TFT color LCD $(320 \times 240$ pixels)
Display color: Selectable from 12 options for trend/ bar graphs
Background color: Selectable from white or black

## - Display

Control group display
Number of loops covered: 4
Number of displays: 4 (4 groups)
Display style:
Controller, faceplate and hybrid style
Tuning display:
Capable of assigning up to 21 parameters
Trend screen
Direction of view: Vertical or horizontal
Number of channels covered: 6 max./screen (group)
Number of trend views on all channels: 36 max.
Number of displays: 6 (6 groups)
Line width: Selectable from 1, 2 and 3 pixels
Screen update interval:
Selectable from $1 \mathrm{~min}, 2 \mathrm{~min}, 5 \mathrm{~min}, 10$ $\min , 20 \mathrm{~min}, 30 \mathrm{~min}, 1 \mathrm{hr}, 2 \mathrm{hr}, 4 \mathrm{hr}$, and $10 \mathrm{hr} / \mathrm{div}$
Program operation status display:
Simultaneously shows the program operation status and current PV readings.
Number of loops covered: 2
Number of displays: 1 (1 group)
Display update interval:
Digital readings $=1 \mathrm{sec}$
Program readings = Same as the trend update interval


Number of display loops/channels

| Imput Type | Number <br> of <br> Control <br> Loops | Number of <br> Channels Covered |
| :--- | :---: | :---: |
| Internal | 2 | 6 <br> (Two loops x PV, SP and <br> OUT readings) |
| Green series communication <br> (option) | 4 | 12 <br> (Four loops x PV, SP and <br> OUT readings) |
| Number of channels <br> covered for measurement | - | 6 |
| Number of channels <br> covered for computation <br> (option) | - | 12 |

Bar graph display:
Direction of view: Vertical or horizontal
Number of channels covered:
6 channels max./display (group)
Number of displays:

$$
6 \text { (6 groups) }
$$

Scale: Configurable within a range from 4 to 12
Reference position = Edge or midpoint
Update interval: 1 sec
Digital display:
Number of channels covered:
6 channels max./display (group)
Number of displays:
6 (6 groups)
Update interval: 1 sec
Overview display:
6 loops max. for control
18 channels max. for measurement
Shows measured values and alarms for all channels. Information display:

Jumps to the trend view of a data item selected by the cursor.
Alarm summary display: Shows the history of alarms.
Event summary display:
Shows a summary of events that have
occurred during program operation.

Control operation summary screen:
Shows a summary of control operation statuses.
Message summary display: Shows the time stamps and contents of messages.
Memory summary display: Shows a list of files stored in internal memory.
Tag display: Tag names for measurement channels (up to 16 alphanumeric characters)
Tag names for control loops (up to 8 alphanumeric characters) Tag comments for control loops (up to 8 alphanumeric characters)
Other on-display elements:
Memory status, scale values (0\%, 100\% can be turned on/off), scales ( 10 scales max.), grid (selectable from a range of 4 to 12 divisions) with hour:min indications, date and time (year/month/day and hour:minute:second indications), trip line (selectable from 1-, 2- and 3-pixel thickness options), messages (of up to 16 characters and 8 types), and alarm marks
Data reference function:
Display the retrieved data.
Display format: Bisectional or full-screen view
Time axis: Can be upscaled, downscaled, and scrolled.
Automatic screen switching
Switching interval
$5 \mathrm{sec}, 10 \mathrm{sec}, 20 \mathrm{sec}, 30 \mathrm{sec}$, or 1 min
LCD back light saver function
Timer setpoint: 1, 2, 5, 10, 20 or 60 min

## CONTROL FUNCTIONS

Control mode
Select from three control modes, i.e., singleloop, cascade control, and loop control with PV switching, for every two loops.
Note) The control mode is fixed to singleloop control for loops 5 and 6.

## Control computation functions

Continuous PID control, Relay on/off control, time proportional PID control

PID Control

| PID Control mode | Operation mode | Operating status | PID control method | Bump of control output |
| :---: | :---: | :---: | :---: | :---: |
| Standard PID control mode | Fixed point control operation | Local and cascade control except cascade secondary loop control | PV derivative type PID | Yes |
|  |  | Remote or secondary cascade loop control | Deviation derivative type PID | Yes |
|  | Programmed control operation | Local and cascade control except secondary cascade loop control, hold or soak | PV derivative type PID | Yes |
|  |  | During programmed operation (without status of hold or soak) or secondary cascade loop control | Deviation derivative type PID | Yes |
| Fixed point Control Mode | Fixed point control operation | Local and cascade control except cascade secondary loop control | PV derivative type PID | Yes |
|  |  | Remote or cascade secondary cascade loop control | PV derivative type PID | Yes |
|  | Programmed control operation | Local, hold and soak | PV derivative type PID | No |
|  |  | Programmed operation (without status of hold) or secondary cascade loop control | PV derivative type PID | Yes |

*The secondary cascade loop is secondary loop of cascade control that is selected from the cascade mode (auto, manual, cascade)
PID parameter: 8 sets/loop for each control mode
Points of zone PID switching: 6 max.
"Super" function (overshoot prevention)
Tracking functions: SP tracking PV tracking
Anti-reset windup function
(over-integration prevention function)
Control interval: 250, 500 or 1000 ms

## Operation mode switching

- Switching among remote, local, and program modes
- Switching among manual, auto, and cascade modes
- Run/stop mode switching

Stop mode: Outputs the preset output value.

- Switching between Execute/Stop options of auto-tuning Principle of auto-tuning: Limit cycle method


## Setting ranges of control parameters

Proportional band: 0.1 to $999.9 \%$
Integral time: 1 to 6000 sec , or off (for manual reset)
Derivative time: 1 to 6000 sec , or off
On-off control hysteresis wideth:
0.0 to $100.0 \%$ of measurement range

Preset output value: -5.0 to $105.0 \%$ of output
(Provided in case of control computation being stopped, PV input being in a burnout state, or instrument input being abnormal)
Output limiter:
Setting range: -5.0 to $105.0 \%$ for both high/low limits
Shutdown function:
Can provide a manipulated output of up to 0 mA when in manual mode operation with $4-20 \mathrm{~mA}$ output (shuts down the output for values smaller than $-5.0 \%$ ).
Output rate-of-change limiter:
Off, or a value from 0.1 to $100.0 \% / \mathrm{sec}$

## ALARM FUNCTIONS

## - Control Alarm

Types of control alarm:
PV high limit, PV low limit, high limit of deviation,low limit of deviation, deviation high and low limits, deviation within high and low limits, SP high limit, SP low limit, OUT high limit, and OUT low limit
Other alarm type:
Fault diagnosis, fail output
Stand-by action:
Turns off PV/SP alarm from starting control until steady condition
Alarm output: 6 points/ 2 loops (transistor output 4 points, relay output 2 points)
Alarm setting: 4 types/ loop
Hysteresis: Can set each alarm setting
Display: The status is shown in the digital display in case of alarm. A common alarm indication is also displayed. The alarm behavior: nonhold or hold-type can be selectable for common to all channels

## - Measurement Alarm

Types of alarm:
High limit, low limit, differential high limit, differential low limit, high limit of rate-ofchange, low limits of rate-of-change, high limit of delay, and low limits of delay (alarm delay)
Alarm delay time: 1 to $3600 \mathrm{sec}(1 \mathrm{hr})$
Time interval of rate-of-change alarm: Measuring interval $\times 1$ to 15
Alarm output: 6 points (option) *alarm output can be assigned to control output
Number of setting: Max. 4/ each channel
Hysteresis: ON ( $0.5 \%$ of span)/ OFF selectable (common to all channels and all levels)
Display: The status is shown in the digital display in case of alarm. A common alarm indication is also displayed. The alarm behavior: nonhold or hold-type can be selectable or common to all channels

## INPUT SECTION

## - Specifications Common to Control and Measurement Inputs

Thermocouple burnout:
Switchable between ON/OFF options of detection on a channel basis. Switchable between burnout upscale/ downscale options
Integral time of A/D converter: Select from the options of $20 \mathrm{~ms}(50 \mathrm{~Hz})$, $16.7 \mathrm{~ms}(60 \mathrm{~Hz}) 100 \mathrm{~ms}(50 / 60 \mathrm{~Hz})$ and AUTO (automatic switching between 20 ms and 16.7 ms depending on the power supply frequency).

## - Control Input

Number of inputs: 5
Input interval:
250,500 or 1000 ms , synchronized with the control period
Input type: DC voltage (DCV), thermocouple (TC), resistance temperature detector (RTD), DC current (DCA) with external shunt resistor
Linear scaling:
Input ranges capable of scaling:
Thermocouple (TC), resistance tempera-
ture detector (RTD), and DC voltage
(DCV)

Available range of scaling: -30000 to 30000 , with a span smaller than 30000
Decimal point position: Selectable by user
Unit: Can be set by user, using up to 6 characters.

## Configuration of input/output signal

Measurement input computation: Input processing, square root extraction (0.0 to $5.0 \%$ low level cutoff), 10 -segment linealizer, and 10 -segment linearizer biasing, and bias addition (from -100.0 to 100.0\% of measuring range), first order lag filter (time constant $=1$ to 120 sec , or off)
Auxiliary computation input:
Input processing, square root extraction ( 0.0 to $5.0 \%$ low level cutoff), bias addition (from -100.0 to $100.0 \%$ of measuring range), ratio multiplication ( 0.001 to 9.999 ), and first order lag filter (time constant $=1$ to 120 sec , or off)
Table of Control Input Specifications

| Input type | Range | Measuring range |
| :---: | :---: | :---: |
| DCV <br> - applicable to linear scaling only | 20 mV | -20.00 to 20.00 mV |
|  | 60 mV | -60.00 to 60.00 mV |
|  | 200 mV | -200.0 to 200.0 mV |
|  | 2 V | -2.000 to 2.000 V |
|  | 6 V | -6.000 to 6.000 V |
|  | 20 V | -20.00 to 20.00 V |
|  | 50 V | -50.00 to 50.00 V |
| TC | $\mathrm{R}^{*}$ | 0.0 to $1760^{\circ} \mathrm{C}$ |
|  | $\mathrm{S}^{*} 1$ | 0.0 to $1760^{\circ} \mathrm{C}$ |
|  | ${ }^{*}{ }^{1}$ | 0.0 to $1820^{\circ} \mathrm{C}$ |
|  | K ${ }^{+1}$ | -200.0 to $1370^{\circ} \mathrm{C}$ |
|  | $\mathrm{E}^{* 1}$ | -200.0 to $800^{\circ} \mathrm{C}$ |
|  | $\mathrm{J}^{* 1}$ | -200.0 to $1100^{\circ} \mathrm{C}$ |
|  | $\mathrm{T}^{*} 1$ | -200.0 to $400^{\circ} \mathrm{C}$ |
|  | $\mathrm{N}^{*}$ | 0.0 to $1300^{\circ} \mathrm{C}$ |
|  | W ${ }^{\text {2 }}$ | 0.0 to $2315^{\circ} \mathrm{C}$ |
|  | L*3 | -200.0 to $900^{\circ} \mathrm{C}$ |
|  | $\mathrm{U}^{+3}$ | -200.0 to $400^{\circ} \mathrm{C}$ |
|  | PLATINEL | 0.0 to $1400.0^{\circ} \mathrm{C}$ |
|  | PR40-20 | 0.0 to $1900.0^{\circ} \mathrm{C}$ |
|  | W3Re/W25Re | 0.0 to $2400.0^{\circ} \mathrm{C}$ |
| RTD*5 | Pt100*4 | -200.0 to $600.0^{\circ} \mathrm{C}$ |
|  | JPt100*4 | -200.0 to $550.0^{\circ} \mathrm{C}$ |
| Standardized signal | 1 to 5 V | 1.000 to 5.000 V |

*1: R, S, B, K, E, J, T, N : IEC584-1 (1995), DIN IEC584, JIS C1602-1995
*2: W : W-5\% Rd/W-26\% Rd (Hoskins Mfg. Co.), ASTM E988
*3: L : Fe-CuNi, DIN43710, U : Cu-CuNi - DIN43710
*4: Pt100 : JIS C1604-1997, IEC751-1995, DIN IEC751-1996
JPt100 : JIS C1604-1989, JIS C1606-1989
*5: Measuring current : $i=1 \mathrm{~mA}$

## Measurement input

Number of inputs: 6
Measuring interval:
1 or 2 sec ( 2 sec , if the integral time of $A / D$ converter is 100 ms )
Input type: DC voltage (DCV), thermocouple (TC), resistance temperature detector (RTD), Operation log (DI), DC current (DCA) with external shunt resistor

## Measurement Input Ranges and Measuring Ranges

| Input type | Input Range | Measuring Range |
| :---: | :---: | :---: |
| DCV | 20 mV | -20.00 to 20.00 mV |
|  | 60 mV | -60.00 to 60.00 mV |
|  | 200 mV | -200.0 to 200.0 mV |
|  | 2 V | -2.000 to 2.000 V |
|  | 6 V | -6.000 to 6.000 V |
|  | 20 V | -20.00 to 20.00 V |
|  | 50 V | -50.00 to 50.00 V |
| TC | $\mathrm{R}^{*}$ | 0.0 to $1760.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{S}^{*} 1$ | 0.0 to $1760.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{B}^{* 1}$ | 0.0 to $1820.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{K}^{* 1}$ | -200.0 to $1370.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{E}^{* 1}$ | -200.0 to $800.0^{\circ} \mathrm{C}$ |
|  | ${ }^{\text {J }}$ | -200.0 to $1100.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{T}^{*} 1$ | -200.0 to $400.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{N}^{* 1}$ | 0.0 to $1300.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{W}^{*}$ | 0.0 to $2315.0^{\circ} \mathrm{C}$ |
|  | L* | -200.0 to $900.0^{\circ} \mathrm{C}$ |
|  | $\mathrm{U}^{*} 3$ | -200.0 to $400.0^{\circ} \mathrm{C}$ |
|  | PLATINEL | 0.0 to $1400.0^{\circ} \mathrm{C}$ |
|  | PR40-20 | 0.0 to $1900.0^{\circ} \mathrm{C}$ |
|  | W3Re/W25Re | 0.0 to $2400.0^{\circ} \mathrm{C}$ |
| RTD*5 | Pt100*4 | -200.0 to $600.0^{\circ} \mathrm{C}$ |
|  | JPt100*4 | -200.0 to $550.0^{\circ} \mathrm{C}$ |
| DI | DCV input | OFF: lower than 2.4 V $\mathrm{ON}: 2.4 \mathrm{~V}$ or higher |
|  | Contact input | ON/OFF states |

*1: R, S, B, K, E, J, T, N : IEC584-1 (1995), DIN IEC584, JIS C1602-1995
*2: W : W-5\% Rd/W-26\% Rd (Hoskins Mfg. Co.), ASTM E988
*3: L : Fe-CuNi, DIN43710, U : Cu-CuNi - DIN43710
*4: Pt100 : JIS C1604-1997, IEC751-1995, DIN IEC751-1996
JPt100 : JIS C1604-1989, JIS C1606-1989
*5: Measuring current : $\mathrm{i}=1 \mathrm{~mA}$
Filter function:
Switchable between ON/OFF options of moving average on a channel basis; selectable from 2 to 16 times for the frequency of moving average calculation
Computation
Difference computation:
Allows for calculation of difference between any two channels.
Input ranges capable of difference computation:
DCV, TC and RTD
Linear scaling:
Input ranges capable of scaling: DCV, TC, RTD
Available range of scaling: -30000 to 30000
Decimal point position: Selectable by user
Engineering unit:
Can be set by user, using up to 6 characters.
Square root scaling:
Input ranges capable of scaling: DCV
Available range of scaling: -30000 to 30000
Decimal point position: Selectable by user

Engineering unit:
Can be set by user, using up to 6 characters.

## STORAGE FUNCTIONS

External storage medium:
Select from the following options when ordering.

- 3.5" floppy disk (2HD)
- PCMCIA ATA flash memory card
- Zip disk


## Storage functions:

Store internal control loops' data (PV, SP and OUT of internal loops), Green series communication loops' data (PV, SP and OUT of connected Green series communication), measured data, and computed data.

PV, SP and OUT of internal loops: assigned from 101 to 106 CH
PV, SP and OUT of Green series communication channels: assigned from 201 to 212 CH

Data on 18 channels among the above-noted channels, as well as 6 measurement channels and 12 computation channels, are stored as data files.

Types of Recorded Data

| Data Type | Channel/Loop/System Included in Recording | Data Item |
| :---: | :---: | :---: |
| Display data (i.e., data for graphical screen views) | Measurement channels/computation channels/internal control loops/Green series communication | Minimum/maximum values during time-out period |
| Event data | Measurement channels/computation channels/internal control loops/Green series communication | Measured values for each sampling period |
| TLOG data | Measured/computed data | TLOG data values at TLOG time-out |
| Report data | Measurement channels/computation channels | Values of channels on an hourly/daily/weekly /monthly basis |
| Manual sampling data | Measurement channels/computation channels/internal control loops/Green series communication loops | ASCII-format data input with keys or remotely |
| Alarm summary data | Measurement channels/computation channels/internal control loops/Green series communication loops | Information on the occurrence/cancellation of alarms on channels being recorded |
| Event summary data | Events caused for the system | Occurrence/cancellation of time/PV events |
| Control mode summary data | System (program operation), or each internal control loop or green series communication loops for all other cases | Run/stop, local/remote, and manual/auto/cascade modes switching, hold/ cancellation of hold of programs, wait/ cancellation of wait |

## Method of saving data

Manual saving:
Saves the data when an external storage medium is inserted.

Auto-saving:
Data can be saved by key operation during sampling continuously.
Saving of display data or event data:
Measuring interval:
10 min to 31 days (when in free-trigger mode)
Data is saved at the end of sampling (when trigger is specified)
Interval of data saving
Display data: Synchronized with the waveform update
Event file: Specify the sampling interval.
Sampling interval for event files:
Select from 1 and 2 sec .
Measurement data files:
(1) Event file

Instantaneous values are saved at a specified sampling interval.
(2) Display data file

The maximum and minimum values found during
the display update interval are saved.
Combination of files to be created
(1) Event file (triggers only) and display data file
(2) Display data file only
(3) Event file only

Data format: Binary
Data size per channel:
Display data: Control data $=4$ bytes/data item Measurement data $=4$ bytes/data item Computation data $=8$ bytes/data item
Event data: $\quad$ Control data $=2$ bytes/data item Measurement data $=2$ bytes/data item Computation data $=4$ bytes/data item
Sampling time:

- Tested for manual saving on a floppy disk.

When creating a display data file only:
Test conditions:
4 control loops, 6 measurement channels, 8 computation channels, $30 \mathrm{~min} /$ div display update interval (data save interval of 60 sec )
Number of data items per channel $=1,200,000$
bytes/ $(4 \times 4$ bytes $+6 \times 4$ bytes $+8 \times 8$ bytes $)=$ approx. 11,538*

* Specified as 100,000 data items maximum.

Sampling time per file $=11,538 \times 60 \mathrm{sec}=692,307$
sec = approx. 8 days
When creating an event file only:
Test conditions:
8 measurement channels, 8 computation channels, 1 -sec data save interval
Number of data items per channel $=1,200,000$ bytes $/(4 \times 2$ bytes $+6 \times 2$ bytes $+8 \times 4$ bytes $)=$ approx. 23,076*

* Specified as 120,000 data items maximum.

Sampling time per file $=23,076$ ( $1 \mathrm{sec}=23,076 \mathrm{sec}$ = approx. 6 hours
When creating both a display data file and an event file: Display data file size $=900,000$ bytes, where a maximum number of data items is 75,000 Event data file size $=300,000$ bytes, where a maximum number of data items is 30,000 Note that the number of files created varies depending on the capacity of storage medium if a Zip drive or an ATA memory card is used.
Examples of sampling time

Test conditions:
2 control loops, 6 measurement channels, and no computati on channels
Display Data File Only

| Display Update <br> Interval <br> (Min/Div) | 1 | 5 | 20 | 30 | 60 | 240 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Data save <br> interval (sec) | 2 | 10 | 40 | 60 | 120 | 480 |
| Sampling <br> time (Approx.) | 13 hrs | 69 hrs | 11 days | 17 days | 34 days | 138 days |

Event Data File Only

| Data save <br> interval (sec) | 1 | 5 | 30 | 120 |
| :--- | :---: | :---: | :---: | :---: |
| Sampling <br> time (Approx.) | 13 hrs | 69 hrs | 17 days | 69 days |

Display Data File and Event Data File
Display Data File

| Display Update <br> Interval <br> (Min/Div) | 1 | 5 | 20 | 30 | 60 | 240 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Data save <br> interval (sec) | 2 | 10 | 40 | 60 | 120 | 480 |
| Sampling <br> time (Approx.) | 10 hrs | 2 days | 8 days | 13 days | 26 days | 104 days |

Event Data File Only

| Data save <br> interval (sec) | 1 | 5 | 30 | 120 |
| :--- | :---: | :---: | :---: | :---: |
| Sampling <br> time (Approx.) | 3 hrs | 17 hrs | 4 days | 17 days |

Test conditions:
4 control loops, 6 measurement channels, and no computation channels
Display Data File Only

| Display Update <br> Interval <br> (Min/Div) | 1 | 5 | 20 | 30 | 60 | 240 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Data save <br> interval (sec) | 2 | 10 | 40 | 60 | 120 | 480 |
| Sampling <br> time (Approx.) | 9 hrs | 46 hrs | 7 days | 11 days | 23 days | 92 days |

Event Data File Only

| Data save <br> interval (sec) | 1 | 5 | 30 | 120 |
| :--- | :---: | :---: | :---: | :---: |
| Sampling <br> time (Approx.) | 9 hrs | 46 hrs | 11 days | 46 days |

Display Data File and Event Data File
Display Data File

| Display Update <br> Interval <br> (Min/Div) | 1 | 5 | 20 | 30 | 60 | 240 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Data save <br> interval (sec) | 2 | 10 | 40 | 60 | 120 | 480 |
| Sampling <br> time (Approx.) | 6 hrs | 34 hrs | 5 days | 8 days | 17 days | 69 days |

Event Data File Only

| Data save <br> interval (sec) | 1 | 5 | 30 | 120 |
| :--- | :---: | :---: | :---: | :---: |
| Sampling <br> time (Approx.) | 2 hrs | 11 hrs | 69 hrs | 17 days |

Manually sampled data
Storage trigger: Key input or contact input
Data format: ASCII
Maximum number of data items stored: 50
TLOG data (only when equipped with computation option)
Storage trigger: Data at the moment TLOG timeout is saved.
Report data (only when equipped with report option)
Report type: Hourly report, daily report, a combination of daily and weekly reports, and a combination of daily and monthly reports
Data format: ASCII
Trigger functions:
Event file: Select the mode from FREE, TRIG and ROTATE options.
Display data and event files: Select the mode from TRIG and ROTATE options.
Display copy functions:
Copying method: By means of key operation
Data format: PNG
Output destination:
External storage medium or communication output

## ■ HARDWARE

## - Construction

Angle of mounting:
Backward tilt of up to $30^{\circ}$; no tilt is allowed on either side, however.
Thickness of mounting panel:
2 to 26 mm
Material: $\quad$ Case $=$ Steel plate Bezel = Polycarbonate
Color of coating: Case = Pale cobalt blue (equivalent to Munsell 2.0B5.0/1.7)
Bezel = Light charcoal gray (equivalent to Munsell 10B3.6/0.3)
Front panel:
Dust- and drip-proof (compliant to IEC529IP65, NEMA No. 250 Type 4 [except for icing tests])
External dimensions:

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144 \mathrm{~mm}(\mathrm{~W}) \times 144 \mathrm{~mm}(\mathrm{H}) \times 218(\mathrm{D}) \mathrm{mm}
$$

Weight: Approx. 3.0 kg

## - I/O Signal Specifications

## Control Output

## Current output

Number of outputs: $2 / 2$ loops
Output signal: $\quad 4-20 \mathrm{~mA}$ DC or 0-20 mA DC
Load resistance: $\quad 600 \Omega$ max.
Output accuracy: $\pm 0.1 \%$ of span ( 1 mA or greater)
Ripple current content:
$0.05 \%$ p-p of span ( 1.2 kHz )
Temperature drift: $\pm 200 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ (tested for output section)
Voltage pulse output
Number of outputs: $2 / 2$ loop
Output signal: $\quad$ On-state voltage $=12 \mathrm{~V}$ DC
Load resistance: $600 \Omega \mathrm{~min}$.
Resolution: $0.1 \%$

Relay contact output
Number of outputs: $2 / 2$ loops
Output signal: NC, NO, COM
Contact rating: $\quad \underset{\text { (resistive load) }}{250 \mathrm{~V} \mathrm{AC} / 30 \mathrm{~A}} 30 \mathrm{~V} \mathrm{DC} / 3 \mathrm{~A}$
(resistive load)

## Contact input

Number of inputs: 6/2 loops
Input signal:Voltage-free contact or open collector (TTL or transistor)
Input condition:
On-state voltage:
0.5 V max. ( 30 mADC )

Off input leakage current:
0.25 mA max.

Input configuration: Photocoupler-isolated (two-point common)

## Contact output

Number of relay outputs:

> 2/2 loops

Relay contact rating: $250 \mathrm{~V} \mathrm{AC/1} \mathrm{~A} \mathrm{or} 30 \mathrm{~V}$ DC/1 A (resistive load)
Number of transistor outputs:
4/2 loops

Transistor contact rating:

$$
24 \mathrm{~V} \text { DC/50 mA }
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## Analog input section

Number of control inputs: 5 (isolated)
Input interval: 250, 500 or 1000 ms
Number of monitor inputs:
6 (DCV, TC and DI inputs are isolated)
Input interval: 1 or 2 sec

- Installation Environment Standards

Normal operating conditions:
Ambient temperature:
0 to $50^{\circ} \mathrm{C}$ ( 5 to $40^{\circ} \mathrm{C}$, if a floppy disk or Zip
drive is in operation)
Ambient humidity:
20 to $80 \%$ RH (at 5 to $40^{\circ} \mathrm{C}$ )
Vibration: 10 to $60 \mathrm{~Hz}, 0.2 \mathrm{~m} / \mathrm{s}^{2}$
Mechanical shock:
Not allowed.
Transport and storage conditions:
Ambient temperature:
-25 to $60^{\circ} \mathrm{C}$
Ambient humidity:
5 to $95 \% \mathrm{RH}$ (non-condensing)
Vibration: 10 to $60 \mathrm{~Hz}, 4.9 \mathrm{~m} / \mathrm{s}^{2}$
Mechanical shock: $392 \mathrm{~m} / \mathrm{s}^{2}$ max. (when housed in a package)

## Safety and EMC Standards

Safety standards:
Certified as conforming to CSA22.2 No.
1010.1; compliant to EN61010-1

Installation category (overvoltage category)
II*1, pollution degree $2^{\star 2}$
*1: Installation category (overvoltage category):
Refers to a numerical index for defining transient overvoltage levels. (This standard also includes the standard of impulse withstanding voltage and applies to electrical equipment powered by stationary equipment such as a switchboard.)
*2: Pollution degree:
Refers to the degree of deposition of a solid, liquid or gas substance that degrades withstanding voltage or surface resistivity. (This standard only applies to normal indoor atmospheres - nonconductive pollution.)
EMC standard:
Compliant to EN61326-1
Power Supply Section
Supply voltage:
100 to 110 V AC $\pm 10 \%$ or 200 to 220 V AC $\pm 10 \%$
Supply frequency:
$50 \mathrm{~Hz} \pm 2 \%$ or $60 \mathrm{~Hz} \pm 2 \%$
Power consumption:

| Supply <br> Voltage | When LCD <br> Saver Is On | When in Normal <br> Operation | Maximum |
| :---: | :---: | :---: | :---: |
| 100 V AC | Approx. 30 VA | Approx. 32 VA | 45 VA |
| 240 V AC | Approx. 42 VA | Approx. 47 VA | 62 VA |

## Isolation

Insulation resistance:
$20 \mathrm{M} \Omega$ min. between each terminal and ground (at 500 V DC)
Withstanding voltage:
Between power supply terminal and ground:
1500 V AC $(50 / 60 \mathrm{~Hz}), 1 \mathrm{~min}$
Between relay contact output terminal and ground: 1500 V AC ( $50 / 60 \mathrm{~Hz}$ ), 1 min
Between measurement input terminal and ground: 1500 V AC (50/60 Hz), 1 min

Between measurement input terminals: 1000 V AC ( $50 / 60 \mathrm{~Hz}$ ), 1 min
Between contact input terminal and ground: 500 V AC $(50 / 60 \mathrm{~Hz}), 1 \mathrm{~min}$
Between current output terminal and ground: 500 V AC ( $50 / 60 \mathrm{~Hz}$ ), 1 min
Between voltage pulse output terminal and ground: 500 V AC ( $50 / 60 \mathrm{~Hz}$ ), 1 min
Between transistor contact output terminal and ground: 500 V AC ( $50 / 60 \mathrm{~Hz}$ ), 1 min
Grounding: JIS Class D
Noise:
Normal mode noise ( $50 / 60 \mathrm{~Hz}$ ):
DC current (DCA):
The peak value including a signal component is less than 1.2 times the measuring range.
Thermocouple (TC):
The peak value including a signal component is less than 1.2 times the thermal electromotive force.
Resistance temperature detector (RTD): 50 mV max.
Common mode noise voltage ( $50 / 60 \mathrm{~Hz}$ ): 250 V AC rms max. for all ranges
Inter-channel maximum noise voltage $(50 / 60 \mathrm{~Hz})$ : 250 V AC rms max.
Warm-up time:
30 min minimum after power-on

- Standard Performance Data

| Input Type | Range | Measurement Accuracy (Digital Readings) | Max. resolution of digital display |
| :---: | :---: | :---: | :---: |
| DC voltage (DCV) | 20 mV | $\pm(0.1 \%$ of rdg +2 digits) | $10 \mu \mathrm{~V}$ |
|  | 60 mV |  | $10 \mu \mathrm{~V}$ |
|  | 200 mV |  | $100 \mu \mathrm{~V}$ |
|  | 2 V |  | 1 mV |
|  | 6 V |  | 1 mV |
|  | 20 V |  | 10 mV |
|  | 50 V | $\pm(0.1 \%$ of rdg + 3 digits) | 10 mV |
| Thermocouple (TC) - excluding the accuracy of reference junction compensation | R | $\pm\left(0.15 \%\right.$ of $\left.r d g+1^{\circ} \mathrm{C}\right)$, where $R$ and $\mathrm{S}= \pm 3.7^{\circ} \mathrm{C}$ over 0 to $100^{\circ} \mathrm{C}$ and $\pm 1.5^{\circ} \mathrm{C}$ over 100 to $300^{\circ} \mathrm{C} ; \mathrm{B}= \pm 2^{\circ} \mathrm{C}$ over 400 to $600^{\circ} \mathrm{C}$, and is not guaranteed for temperatures below $400^{\circ} \mathrm{C}$. | $0.1{ }^{\circ} \mathrm{C}$ |
|  | S |  |  |
|  | B |  |  |
|  | K | $\pm\left(0.15 \%\right.$ of $\left.r d g+0.7^{\circ} \mathrm{C}\right)$, where the accuracy is $\pm(0.15 \%$ of $r d g+1^{\circ} \mathrm{C}$ ) over -200 to $-100^{\circ} \mathrm{C}$. |  |
|  | E | $\pm\left(0.15 \%\right.$ of rdg $\left.+0.5^{\circ} \mathrm{C}\right)$ |  |
|  | $\begin{aligned} & \mathrm{J} \\ & \mathrm{~T} \end{aligned}$ | $\pm\left(0.15 \%\right.$ of $\left.r d g+0.5^{\circ} \mathrm{C}\right)$, where the accuracy is $\pm(0.15 \%$ of rdg $+0.7^{\circ} \mathrm{C}$ ) over -200 to $-100^{\circ} \mathrm{C}$. |  |
|  | N | $\pm\left(0.15 \%\right.$ of $\left.\mathrm{rdg}+0.7^{\circ} \mathrm{C}\right)$ |  |
|  | W | $\pm\left(0.15 \%\right.$ of $\left.\mathrm{rdg}+1^{\circ} \mathrm{C}\right)$ |  |
|  | L | $\pm\left(0.15 \%\right.$ of rdg $\left.+0.5^{\circ} \mathrm{C}\right)$, where the accuracy is $\pm(0.15 \%$ of |  |
|  | U | rdg $+0.7^{\circ} \mathrm{C}$ ) over -200 to $100^{\circ} \mathrm{C}$. |  |
|  | PLATINEL | 0.0 to $1400.0^{\circ} \mathrm{C}$ |  |
|  | PR40-20 | Not guaranteed over 0 to $450^{\circ} \mathrm{C}$ <br> $\pm\left(0.9 \%\right.$ of $\left.\mathrm{rdg}+16.0^{\circ} \mathrm{C}\right)$ over 450 to $750^{\circ} \mathrm{C}$ <br> $\pm\left(0.9 \%\right.$ of rdg $\left.+6.0^{\circ} \mathrm{C}\right)$ over 750 to $1100^{\circ} \mathrm{C}$ <br> $\pm\left(0.9 \%\right.$ of $\left.r d g+2.0^{\circ} \mathrm{C}\right)$ over 1100 to $1900^{\circ} \mathrm{C}$ |  |
|  | W3Re/ W25Re | $\pm\left(0.3 \%\right.$ of rdg $\left.+2.8^{\circ} \mathrm{C}\right)$ |  |
| Resistance temperature detector (RTD) | Pt100 | $\pm\left(0.15 \%\right.$ of rdg $\left.+0.3^{\circ} \mathrm{C}\right)$ |  |
|  | JPt100 |  |  |

Measurement/reading accuracy:
Tested under the following conditions:
Standard operating conditions:
$23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$
Supply voltage range:
90 to $132 \mathrm{~V} \mathrm{AC} ; 180$ to 250 V AC
Supply frequency range:
$50 / 60 \mathrm{~Hz} \pm 1 \%$ max.
Note: The accuracy performance is tested after a warmup time of at least 30 min and in a location free from such adverse effects on the instrument's operation as mechanical vibration.
Measurement accuracy during scaling: Measurement accuracy during scaling (digits)
$=$ measurement accuracy (digits) +2 digits
where the value is rounded up to the nearest whole number.
Reference junction compensation:
Switchable between INT (internal) and EXT
(external) options (common to all channels).
Reference junction compensation accuracy:
$\pm 1.0^{\circ} \mathrm{C}$ for types R, S, B, W, PR40-20 and
W3Re/W25Re
$\pm 0.5^{\circ} \mathrm{C}$ for types K, J, E, T, N, L, U and
PLATINEL only (during measuring tempera-
ture that is no lower than $0^{\circ} \mathrm{C}$ )
Maximum input voltage:
$\pm 10 \mathrm{~V}$ DC (continuous) for 2 V DC or lower
voltage ranges and TC input
$\pm 30 \mathrm{~V}$ DC (continuous) for 6 and 20 V DC voltage ranges
Input resistance:
$10 \mathrm{M} \Omega$ min. for $2 \mathrm{~V} D C$ or lower voltage ranges and TC input
Approx. $1 \mathrm{M} \Omega$ for 6 and 20 V DC voltage ranges
External input resistance:
$2 \mathrm{k} \Omega$ max. for DCV and TC inputs
$10 \Omega$ max. per wire for RTD input (all three wires must have the same resistance)
Input bias current: 10 nA max.
Interference between channels:
120 dB (when external input resistance is
$500 \Omega$ and the level of input to other channels is 30 V )
Common mode rejection ratio:
$120 \mathrm{~dB}(50 / 60 \mathrm{~Hz} \pm 0.1 \%$, unbalanced
$500 \Omega$ input resistance; tested between
negative input terminal and ground)
Normal mode rejection ratio:
$40 \mathrm{~dB}(50 / 60 \mathrm{~Hz} \pm 0.1 \%)$

## - Other Specification

Clock: Provided with calendar function; can be synchronized by means of external contact
Clock accuracy:
$\pm 100 \mathrm{ppm}$, excluding a time lag (less than 1 sec ) at the time of power-on
Key lock function:
Can be turned on or off; a password can be set for the function.
Login function:
The station can be logged in to by entering a user name, user ID and password. The station can be locked with a password.

## ■ COMMUNICATION FUNCTIONS

## - Ethernet Communication

Medium: Ethernet (10BASE-T)
Basis protocol:
SMTP, HTTP1.0, FTP, TCP, UDP, IP, ARP and ICMP
E-mail function:
Recipient address:
2 address groups (two or more addresses can be specified for each group using no more than 150 characters)
Types of message:
The following pieces of information can be sent via e-mail; for each address group, a selection can be made as to whether or not to send the information. Alarms, appointed time, and reports
Web server function:
Shows screen images, alarms, instantaneous values and other information using Browser software (Internet Explorer 5.0).
FTP client function: Transfers files automatically.
FTP server function:
Acquires or deletes files, or manipulates directories from the host computer, and provides information on the remaining size of memory.
FTP server function: Manipulates directories in an external storage medium, outputs or deletes files from the medium, and provides information on the remaining size of memory.
Real-time monitor function:
Provided.

## - Serial Communication

This type of communication is used for ladder communication, digital indicating controller communication, and modbus communication.
Medium: EIA RS-232 (CX1xx06-x-1-x)
EIA RS-422A/485 (CX1xx06-x-2-x)
Protocol: Dedicated protocol or Modbus protocol Synchronization: Start-stop synchronization
Communication method (RS-422A/485): Four-wire, half-duplex multi-drop connection ( $1: \mathrm{N}$, where $\mathrm{N}=1$ to 31 )
Transfer rate:
1200, 2400, 4800, 9600,19200 , or 38400 bps
Data length: 7 or 8 bits
Number of stop bits: 1
Parity: ODD, EVEN or NONE
Overall communication distance (RS-422A/485): 1.2 km

Communication mode: ASCII for input/output of control and setting data ASCII or binary for output of measured data
Modbus communication:
Operating mode:
RTU MASTER or RTU SLAVE

RTU MASTER:
Provides up to 8 start-of-readout addresses. (Continuous readout is allowed.)
RTU SLAVE:
Outputs measured/computed data, alarm statuses, and so on.

## ■OPTIONS

- Program Setting Functions (/PG1, /PG2)

Program setting functions
Number of program patterns: 4 (/PG1), 30 (/PG2)
Number of segments per program pattern: 99 max.
Number of program segments:
300 max. (as the sum of segments for all program patterns)
Number of program events: 800 max.
Number of program repetitions: 999 max. or infinite Segment time:

0 min:1 sec to $99 \mathrm{hr}: 59 \mathrm{~min}: 59 \mathrm{sec}$
Start/stop of program pattern:
A program pattern can be started(RUN), stopped(RESET), held(Hold) or advanced by means of contact input or instrument operation.
Switching among program patterns:
A program pattern can be switched to another by means of contact input or instrument operation.
Wait function:
Wait time: Off, or $0 \mathrm{~min}: 1 \mathrm{sec}$ to $99 \mathrm{~min}: 59 \mathrm{sec}$
Wait zone: 0 to $10 \%$ of the span of measurement input range
PID parameters switching
Segment PID selection: PID-parameter numbers being used can be selected on a segment basis
Zone PID selection: PID parameter sets are switched depending on the value of the applied PV input

## Time event:

The progress status of a program pattern is provided by means of contact output.
Number of events set:
16 max. per segment
Output: Provided after the lapse of a specified time from the moment of segment switchover.
Range of time lapse:
0 to $99 \mathrm{hr}: 59 \mathrm{~min}: 59 \mathrm{sec}$

## PV event:

Alarm function for measured values/deviations within a program pattern
Number of events set: 16 max.
Event type: PV high limit, PV low limit, high limit of deviation, low limit of deviation, deviation within high and low limits, SP high limit, SP low limit, Out high limit, Out low limit

## Control mode switching

RESET/RUN switching for program
operation: Run/stop status of program operation
Hold/non-Hold options:
The progress of program operation can be placed in a Hold state or non-Hold state while in the Run status of a program.

- Measurement Alarm Output Relay(/A6, /A6R, /A4F, (A4FR)
Number of outputs: 6 (/A6, /A6R, /A4F, /A4FR)
Number of inputs: 8 (for /A6R, A4FR option only)
Relay contact rating: 250 V DC/0.1 A (resistive load) or 250 V AC $(50 / 60 \mathrm{~Hz}) / 3 \mathrm{~A}$
Output configuration: NO-C-NC (switchable between Enable/Disable options, between AND/OR options and between Retain/Don't Retain options)
Remote Control (/A6R, /A4FR)
The following types of control are possible by means of contact input (configurable for up to 8 types):
- Start/stop of memory (signal level)
- External trigger input for event files (trigger of 250 ms or longer)
- Synchronization (adjusts the clock to an appointed time by means of contact input; trigger of 250 ms or longer)
- Start/stop of computation (signal level)
- Resetting of computed data ( 250 ms or longer trigger)
- Manual sampling ( 250 ms or longer trigger)
- Message writing (configurable for up to 8 messages; 250 ms or longer trigger)
- Load setting (configurable for up to 3 loads; 250 ms or longer trigger)
- Alarm acknowledgment (of 250 ms or longer trigger)

FAIL output/end-of-memory output (/A4F, /A4FR)
Provided as a relay output from the backside of the station in case of system failure, prior to the specified time (selectable from 1, 2, 5, $10,20,50$, and 100 hr ) of overwriting a data file for screen views.

## Mathematical Functions (/M1)

With the "/M1" option, it is possible to show and record trend graphs/digital readings for the following types of computation on computation channels.
Number of computation channels: 12
Types of computation:
Standard computations:
Four fundamental arithmetic operations, square roots, absolute values, common logarithm, exponents, powers, relational operations ( $<, \leq,>, \geq,=, \neq$ ), logical operations (AND, OR, NOT, XOR)
Statistical computations:
Average, maximum, minimum, and total values of time-series data
Moving average computation:
A moving average calculation is performed on the results of computation.
Constants: Up to 30 constants can be set as necessary.
Communication-based digital input:
This input can be applied to computational expressions other than statistical ones.
Number of communication-based digital data values: 30 Remote input:

A remote status ( $0 / 1$ ) can be used in a computational expression.
Number of remote-input data values: 8
Report functions:
Report type:
Hourly report, daily report, a combination of daily and weekly reports, and a combination of daily and monthly reports
Type of computation:
Average, maximum, minimum, total
Data format: ASCII

- Three-legs Isolated RTD Input (/N2)

The "/N2" option is an RTD input, the RTD of which has electrically isolated $\mathrm{A}, \mathrm{B}$ and b terminals.

## - 24 V DC/AC Power Supply (/P1)

Specifications of the "/P1" option are as follows:
Rated supply voltage:
24 V DC/AC
Operating supply voltage range:
21.6 to 26.4 V DC/AC

Withstanding voltage:
500 V AC between power supply terminal and ground
Power consumption:

| Supply <br> voltage | When LCD <br> Saver Is On | When in Normal <br> Operation | Maximum |
| :--- | :---: | :---: | :---: |
| 24 V AC | Approx. 17 VA | Approx. 19 VA | 30 VA |
| 24 V AC | Approx. 28 VA | Approx. 32 VA | 45 VA |
| $(50 / 60 \mathrm{~Hz})$ |  |  |  |

## Green Series Communication (/CM1)

The "/CM1" option provides the function for communicating with GREEN series digital indicating controller. Supported controller models are UT3×0, UT $4 \times 0, \mathrm{UT} 5 \times 0$, UT750, and other specific models (UT and UP series with heating/cooling control are classified as "other specific models").

## - Ladder Communication (/CM2)

Ladder communication is a communication protocol used to communicate between an FA-M3 ladder communication module and a programmable controller from another manufacturer.

## APPLICATION SOFTWARE

## - DAQSTANDARD

System requirements:
OS: $\quad$ Windows 98/Me/NT4.0/2000
Processor: MMX Pentium/166 MHz or superior (Pentium II/266 MHz or any other superior processor is recommended.)
Memory: $\quad 32 \mathrm{MB}$ min. ( 64 MB or larger memory is recommended)
Disk device:
CD-ROM drive compatible with Windows 98/Me/NT4.0/2000
Hard disk capacity:
Free space of at least 10 MB ( 100 MB or larger free space is recommended)
Display unit:
A model provided with a display module compatible with Windows $98 / \mathrm{Me} / \mathrm{NT} 4.0 /$ 2000 and capable of handling at least 32000 colors (a display module capable of handling at least 64000 colors is recommended)
Printer: Compatible with Windows $95 / 98 / \mathrm{Me}$ / NT4.0/2000; the printer driver must also be compatible with the OS.
Main functions (as a package):
Configuration software:
External storage medium:
Configures the medium or sets it in set mode.

Configuration via communication:
Configures the station, excluding the communication setting (IP address), or sets it in set mode.
Data viewer:
Number of channels covered for display: 32 per group; 30 groups max.
Display functions:
Waveform views, digital readings, circular graphics, lists, TLOG views, report views, etc.
File connection display:
This function concatenates files created separately during continuous data acquisition because of auto-saving or power failure, and shows the concatenated file on the display (can concatenate files of up to $1,000,000$ data items).
Section computation: Maximum, minimum, average, rms value, $p-p$ value
Data conversion:
This function converts the data format to ASCII, Lotus 1-2-3, or Excel.
Printout: The data viewer prints replayed data.

## MODELS AND SUFFIX CODES


*1: Select both the suffix code for RS-232 or RS-422/485 communication port and the /CM1 option code at the same time
*2: CX1006 must be specified. /A6, /A6R, /A4F, /A4FR can not be specified together.
*3: Be sure to select the suffix code for RS-232 or RS-422/485 communication port. Only an alternative choice is allowed
*4: Effective only for the model with internal loops Only an alternative choice from the options /PG1 and /PG2 is allowed.

## Application Software

| Model | Description | OS |
| :---: | :---: | :---: |
| DXA200-02 | DAQEXPLORER | Windows 98/Me/NT4.0/2000 |
| DXA200-02/XF1 | DAQEXPLORER <br> with auto file conversion function |  |
| DXA310-011 | DAQ-PharmBio |  |
| DXA410-02 | DAQOPC | Windows NT4.0 |
| VA510-01-2 | DAQLOGGER (400 channels) | Windows 95/98/NT4.0/2000 |
| VA510-02-2 | DAQLOGGER (1000 channels) |  |
| VA510-03-2 | DAQLOGGER (1600 channels) |  |
| VA520-01-2 | DAQLOGGER Client (1600 channels) |  |

## - Standard Accessories

| Product | Quantity |
| :--- | :---: |
| Mounting brackets | 2 |
| Terminal screws | 5 |
| User's manual | 1 |
| Zip disk (100 MB) | 1 |
| ATA flash memory card (20 MB) | 1 |

## - Optional Accessories

| Product | Model (part) number | Specification |
| :--- | :---: | :--- |
| Shunt resistor <br> (for screw input terminals) | 415920 | $250 \Omega \pm 0.1 \%$ |
|  | 415921 | $100 \Omega \pm 0.1 \%$ |
|  | 415922 | $10 \Omega \pm 0.1 \%$ |
| 3.5-inch floppy disk | 705900 | $2 \mathrm{HD}(10$ units) |
| Zip disk | A1053MP | 100 MB |
| ATA flash memory card | A1134UN | 20 MB |
| Mounting bracket | B9900CW | - |

## Spare Parts

| Control output module | CXA900-01 |  |
| :--- | :--- | :--- |
|  | CXA900-02 |  |
|  | CXA900-03 |  |
| Control extension DIO module | CXA900-11 |  |

## DIMENSIONS

## Dimensions



Note : If not specified, the tolerance is $\pm 3 \%$.
However, for dimensions less than 10 mm , the tolerance is $\pm 0.3 \mathrm{~mm}$.
Rear View



Control Input terminal Measurement Input terminal

(DIMENSIONS AFTER MOUNTING)

## Panel cutout

Unit : mm (approx. inch)
Single-unit Mounting
Side-by-side Mounting (horizontally)



| Units | $\mathrm{L}_{+}^{+2}(\mathrm{~mm})$ |
| :---: | :---: |
| 2 | 282 |
| 3 | 426 |
| 4 | 570 |
| 5 | 714 |
| 6 | 858 |
| 7 | 1002 |
| 8 | 1146 |
| 9 | 1290 |
| 10 | 1434 |
| n | $(144 \times \mathrm{n})-6$ |

Note : If not specified, the tolerance is $\pm 3 \%$. However, for dimensions less than 10 mm , the tolerance is $\pm 0.3 \mathrm{~mm}$.

## Power Supply Terminal



RS-422-A/485 Terminal


## FOUNDATION Fieldbus Terminal



## Measurement Input Terminals



Control input terminals


Control output and contact I/O terminals


Option Terminals (CX1006)

## /A6



Alarm output relays
/A4F
FAIL

/A6R

| 6 | 5 | 4 | 3 | 2 | 1 |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| NC | NC | NC | NC | NC | NC | 6 | 3 | C |
| C | C | C | C | C | C | 7 | 4 | 1 |
| NO | NO | NO | NO | NO | NO | 8 | 5 | 2 |


| IA4FR |
| :--- |
| FAIL |
| NC           <br> C NC NC  NC NC  NC 6 3 C <br> NO C C  C C  C 7 4 1 <br>  NO NO  NO NO  NO 8 5 2 |

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